

# Ching-An Wu

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<b>COMPUTER SKILLS</b>	Python, C/C++, MATLAB, SQL, Git, Linux/Unix, Scala, PHP, HTML, CSS	
<b>EDUCATION</b>	<b>KTH Royal Institute of Technology</b> Master of Science in Systems, Control and Robotics, EECS	Aug 2017 – present
	<b>National Taiwan University</b> Bachelor of Science in Mechanical Engineering Activities and Societies: NTU Pop Dance Club, Association of HSNU Alumni, NTU Cocktail	Sep 2011 – Jun 2015
<b>RESEARCH PROJECTS</b>	<b>Reinforcement Learning for Robotic Manipulation, KTH</b> <ul style="list-style-type: none"><li>Carried out research in reinforcement learning for robotic manipulation tasks at Robotics, Perception and Learning Lab, KTH</li><li>Investigated sample efficiency for reinforcement learning given different observation and action spaces on a manipulation task.</li><li>Improved sample efficiency by adding pre-and-post- preprocessing blocks based on established methods such as object detection and inverse kinematics</li></ul>	March 2019 – present
	<b>A Convolutional Neural Network model for Robot Grasp Evaluation, KTH</b> <ul style="list-style-type: none"><li>Built a robot grasp evaluation function with a convolutional neural network</li><li>Designed a data pipeline to handle the imbalanced datasets by using data augmentation techniques such as random sampling</li><li>Assessed two models with different model settings based on their accuracy and f1-score</li></ul>	Sep 2018 – Dec 2018
	<b>Character-Level Text Classification with Different RNN Architectures, KTH</b> <ul style="list-style-type: none"><li>Built a character-level recurrent neural network to classify text to the respective categories</li><li>Introduced different layers such as LSTM and GRU and benchmarked performance</li><li>Evaluated the performance using different optimizers such as SGD, Adam and AdaGrad</li></ul>	May 2018 – Jun 2018
	<b>Robot with Multiple Dynamic Movement Patterns, NTU</b> <ul style="list-style-type: none"><li>Developed a bio-inspired bipedal robot with the Teensy board with Professor Pei-Chun Lin</li><li>Built mathematical models using Lagrange equations</li><li>Analyzed and simulated the dynamics of the robot using MATLAB</li><li>Project received the National Science Council Research Creativity Award</li></ul>	Feb 2014 – Jan 2015
<b>EXPERIENCE</b>	<b>Corporal, Republic of China Army</b> <ul style="list-style-type: none"><li>Duty officer for company of 30 people every other week</li><li>Responsible for administrative tasks</li><li>Repaired and maintain wheeled armored vehicles</li></ul>	Aug 2015 – Jul 2016
	<b>Microsoft Student Partner, Microsoft</b> <ul style="list-style-type: none"><li>Received technical training from Microsoft Most Valuable Professionals</li><li>Developed Windows Store apps</li></ul>	Jul 2013 – Aug 2013
	<b>Vice Director, Association of HSNU Alumni, NTU</b> <ul style="list-style-type: none"><li>Organized alumni events such as high school uniform day, HSNU alumni week and orientation activities</li><li>Responsible for sponsorship of local businesses in alumni events</li><li>Increased participation of alumni in organized activities</li></ul>	Sep 2012 – Jan 2013
<b>LANGUAGES</b>	Mandarin Chinese (native), English (fluent)	
<b>REFERENCE</b>	<b>Michael Welle</b> PhD student Robotics, Perception and Learning Lab, KTH Email: mwelle@kth.se	